



**Data:** 14/05/2010  
**Semestre:** 2010.1  
**Curso:** Engenharia de Alimentos  
**Disciplina:** Álgebra Linear  
**Prova:** II

1. 4 pts. Dados os vetores em  $\mathbb{R}^4$ :

$$\underline{d}_1 = \begin{pmatrix} 1 \\ 1 \\ 0 \\ 0 \end{pmatrix} \quad \underline{d}_2 = \begin{pmatrix} 0 \\ 1 \\ 1 \\ 0 \end{pmatrix} \quad \underline{d}_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \\ 1 \end{pmatrix} \quad \underline{d}_4 = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 2 \end{pmatrix} \quad \underline{d}_5 = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}$$

- Mostre que os vetores  $\underline{d}_1, \underline{d}_2, \underline{d}_3, \underline{d}_4$  formam uma base em  $\mathbb{R}^4$ .
- Encontre uma relação entre as coordenadas em relação a base canônica e a base  $(\underline{d}_1, \underline{d}_2, \underline{d}_3, \underline{d}_4)$ .
- Encontre as coordenadas do vetor  $\underline{d}_5$  na base  $(\underline{d}_1, \underline{d}_2, \underline{d}_3, \underline{d}_4)$ .
- Encontre as coordenadas antigas dos vetores básicos novos.
- Encontre as coordenadas novas dos vetores básicos antigos.

**Solution:**

(a)

$$\begin{aligned} (\underline{D} \mid \underline{I}) &= \left( \begin{array}{cccc|cccc} \mathbf{1} & 0 & 0 & 1 & 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 2 & 0 & 0 & 0 & 1 \end{array} \right) \sim \left( \begin{array}{cccc|cccc} 1 & 0 & 0 & 1 & 1 & 0 & 0 & 0 \\ 0 & \mathbf{1} & 0 & -1 & -1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 2 & 0 & 0 & 0 & 1 \end{array} \right) \sim \\ & \left( \begin{array}{cccc|cccc} 1 & 0 & 0 & 1 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & -1 & -1 & 1 & 0 & 0 \\ 0 & 0 & \mathbf{1} & 1 & 1 & -1 & 1 & 0 \\ 0 & 0 & 1 & 2 & 0 & 0 & 0 & 1 \end{array} \right) \sim \left( \begin{array}{cccc|cccc} 1 & 0 & 0 & 1 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & -1 & -1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 & 1 & -1 & 1 & 0 \\ 0 & 0 & 0 & \mathbf{1} & -1 & 1 & -1 & 1 \end{array} \right) \sim \\ & \left( \begin{array}{cccc|cccc} 1 & 0 & 0 & 0 & 2 & -1 & 1 & -1 \\ 0 & 1 & 0 & 0 & -2 & 2 & -1 & 1 \\ 0 & 0 & 1 & 0 & 2 & -2 & 2 & -1 \\ 0 & 0 & 0 & 1 & -1 & 1 & -1 & 1 \end{array} \right) \end{aligned}$$

(b) Temos:  $\underline{x}_A = \underline{D} \underline{x}_N \Leftrightarrow \underline{x}_N = \underline{D}^{-1} \underline{x}_A$ , por completo:

$$\underline{x}_A = \begin{pmatrix} 1 & 0 & 0 & 1 \\ 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 2 \end{pmatrix} \underline{x}_N \Leftrightarrow \underline{x}_N = \begin{pmatrix} 2 & -1 & 1 & -1 \\ -2 & 2 & -1 & 1 \\ 2 & -2 & 2 & -1 \\ -1 & 1 & -1 & 1 \end{pmatrix} \underline{x}_A$$

(c) Em relação a base  $(\underline{d}_1, \underline{d}_2, \underline{d}_3, \underline{d}_4)$ :

$$\underline{d}_5 = \begin{pmatrix} 2 & -1 & 1 & -1 \\ -2 & 2 & -1 & 1 \\ 2 & -2 & 2 & -1 \\ -1 & 1 & -1 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} = \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \end{bmatrix} = \underline{d}_1 + \underline{d}_3$$

(d) As coordenadas antigas dos vetores básicos novos estão nas colunas da  $\underline{D}$ :

$$\underline{d}_1 = \begin{pmatrix} 1 \\ 1 \\ 0 \\ 0 \end{pmatrix} \quad \underline{d}_2 = \begin{pmatrix} 0 \\ 1 \\ 1 \\ 0 \end{pmatrix} \quad \underline{d}_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \\ 1 \end{pmatrix} \quad \underline{d}_4 = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 2 \end{pmatrix}$$



(e) As coordenadas novas dos vetores bsicos antigos estão nas colunas da  $\underline{\underline{D}}^{-1}$ :

$$\underline{\underline{e}}_1 = \begin{bmatrix} 2 \\ -2 \\ 2 \\ 1 \end{bmatrix} \quad \underline{\underline{e}}_2 = \begin{bmatrix} -1 \\ 2 \\ -2 \\ 1 \end{bmatrix} \quad \underline{\underline{e}}_3 = \begin{bmatrix} 1 \\ -1 \\ 2 \\ -1 \end{bmatrix} \quad \underline{\underline{e}}_4 = \begin{bmatrix} -1 \\ 1 \\ -1 \\ 1 \end{bmatrix}$$

2. 2 pts. Uma aplicao linear,  $f : \mathbb{R}^3 \mapsto \mathbb{R}^3$  dado pela sua matriz:

$$\underline{\underline{A}} = \begin{pmatrix} 0 & 1 & 1 \\ 1 & -1 & 0 \\ 1 & 0 & 1 \end{pmatrix}$$

- Encontrar o núcleo e a sua dimensão.
- Encontrar a dimenso e uma base da imagem,  $f(\mathbb{R}^3)$ .
- Encontrar o conjunto:  $\{\underline{\underline{x}} \in \mathbb{R}^3 \mid f(\underline{\underline{x}}) = (0, 1, 1)\}$ .
- $f$  tem inversa?

**Solution:**

(a)

$$\underline{\underline{A}} = \begin{pmatrix} 0 & 1 & 1 \\ 1 & -1 & 0 \\ 1 & 0 & 1 \end{pmatrix} \sim \begin{pmatrix} 0 & \mathbf{1} & 1 \\ 1 & -1 & 0 \\ 0 & 1 & 1 \end{pmatrix} \sim \begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} \underline{\underline{x}} = \underline{\underline{0}} \Leftrightarrow$$

$$x_2 + x_3 = 0 \wedge x_1 + x_3 = 0 \Leftrightarrow x_3 = t \wedge x_1 = x_2 = -t \Leftrightarrow \underline{\underline{x}} = t \begin{pmatrix} -1 \\ -1 \\ 1 \end{pmatrix}, \quad t \in \mathbb{R}$$

A dimenso do ncleo  $n - \rho_{\underline{\underline{A}}} = 3 - 2 = 1$ .

- A dimenso da imagem  $\rho_{\underline{\underline{A}}} = 2$ . Para encontrar uma base desta, selecionamos 2 vetores linearmente independentes das colunas do  $\underline{\underline{A}}$ , por exemplo:  $\underline{\underline{a}}_1 = (0, 1, 1)$  e  $\underline{\underline{a}}_2 = (1, -1, 0)$ .
- Observamos que  $f(\underline{\underline{i}}) = (0, 1, 1)$ , ou seja:  $\underline{\underline{x}} = \underline{\underline{i}}$  uma soluo *particular* do sistema homogênea  $f(\underline{\underline{x}}) = (0, 1, 1)$ . Obtemos a soluo completa deste, adicionando a soluo completa do sistema homegênea (o ncleo):

$$f(\underline{\underline{x}}) = \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} \Leftrightarrow \underline{\underline{x}} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + t \begin{pmatrix} -1 \\ -1 \\ 1 \end{pmatrix}, \quad t \in \mathbb{R}$$

(d) Por  $\rho_{\underline{\underline{A}}} = 2 < 3$ ,  $\underline{\underline{A}}$  não é regular, assim  $f$  não tem inversa.

3. 4 pts. Dados os vetores em  $\mathbb{R}^4$ :

$$\underline{\underline{v}}_1 = \begin{pmatrix} 1 \\ 2 \\ 4 \\ -2 \end{pmatrix} \quad \underline{\underline{v}}_2 = \begin{pmatrix} 1 \\ 0 \\ 3 \\ -2 \end{pmatrix} \quad \underline{\underline{v}}_3 = \begin{pmatrix} -1 \\ 1 \\ -3 \\ 5 \end{pmatrix} \quad \underline{\underline{v}}_4 = \begin{pmatrix} -1 \\ 0 \\ -3 \\ 1 \end{pmatrix}$$

e uma aplicao linear,  $f : \mathbb{R}^4 \mapsto \mathbb{R}^4$ :

$$f(\underline{\underline{v}}_1) = \underline{\underline{v}}_1 + \underline{\underline{v}}_2, \quad f(\underline{\underline{v}}_2) = -\underline{\underline{v}}_1 + \underline{\underline{v}}_2, \quad f(\underline{\underline{v}}_3) = \underline{\underline{v}}_3 + \underline{\underline{v}}_4, \quad f(\underline{\underline{v}}_4) = -\underline{\underline{v}}_3 + \underline{\underline{v}}_4$$

- Mostrar que os vetores  $\underline{\underline{v}}_1, \underline{\underline{v}}_2, \underline{\underline{v}}_3, \underline{\underline{v}}_4$  formam uma base em  $\mathbb{R}^4$ .
- Encontrar a matriz,  $\underline{\underline{A}}$ , em relao a base canônica (no domínio e na imagem).
- Encontrar a matriz,  $\underline{\underline{B}}$ , em relao da base  $(\underline{\underline{v}}_1, \underline{\underline{v}}_2, \underline{\underline{v}}_3, \underline{\underline{v}}_4)$  (no domínio e na imagem).
- Sendo  $U = \text{ger}(\underline{\underline{v}}_1, \underline{\underline{v}}_2)$ , mostre que  $f(U) = U$ .



(e) Sendo  $\underline{\underline{V}}$  a matriz contendo os vetores  $\underline{v}_1, \underline{v}_2, \underline{v}_3, \underline{v}_4$  em colunas, mostre:  $\underline{\underline{B}} = \underline{\underline{V}}^{-1} \underline{\underline{A}} \underline{\underline{V}}$ .

**Solution:**

(a) Mostramos que os vetores formam uma base e encontramos a inversa:

$$\begin{aligned} (\underline{\underline{V}} | \underline{\underline{I}}) &= \left( \begin{array}{cccc|cccc} \mathbf{1} & 1 & -1 & -1 & 1 & 0 & 0 & 0 \\ 2 & 0 & 1 & 0 & 0 & 1 & 0 & 0 \\ 4 & 3 & -3 & -3 & 0 & 0 & 1 & 0 \\ -2 & -2 & 5 & 1 & 0 & 0 & 0 & 1 \end{array} \right) \sim \left( \begin{array}{cccc|cccc} 1 & 1 & -1 & -1 & 1 & 0 & 0 & 0 \\ 0 & -2 & 3 & 2 & -2 & 1 & 0 & 0 \\ 0 & -1 & 1 & 1 & -4 & 0 & 1 & 0 \\ 0 & 0 & 3 & -1 & 2 & 0 & 0 & 1 \end{array} \right) \sim \\ &\left( \begin{array}{cccc|cccc} 1 & 1 & -1 & -1 & 1 & 0 & 0 & 0 \\ 0 & -2 & 3 & 2 & -2 & 1 & 0 & 0 \\ 0 & \mathbf{1} & -1 & -1 & 4 & 0 & -1 & 0 \\ 0 & 0 & 3 & -1 & 2 & 0 & 0 & 1 \end{array} \right) \sim \left( \begin{array}{cccc|cccc} 1 & 0 & 0 & 0 & -3 & 0 & 1 & 0 \\ 0 & 0 & \mathbf{1} & 0 & 6 & 1 & -2 & 0 \\ 0 & 1 & -1 & -1 & 4 & 0 & -1 & 0 \\ 0 & 0 & 3 & -1 & 2 & 0 & 0 & 1 \end{array} \right) \sim \\ &\left( \begin{array}{cccc|cccc} 1 & 0 & 0 & 0 & -3 & 0 & 1 & 0 \\ 0 & 0 & \mathbf{1} & 0 & 6 & 1 & -2 & 0 \\ 0 & 1 & 0 & -1 & 10 & 1 & -3 & 0 \\ 0 & 0 & 0 & -1 & -16 & -3 & 6 & 1 \end{array} \right) \sim \left( \begin{array}{cccc|cccc} 1 & 0 & 0 & 0 & -3 & 0 & 1 & 0 \\ 0 & 0 & \mathbf{1} & 0 & 6 & 1 & -2 & 0 \\ 0 & 1 & 0 & -1 & 10 & 1 & -3 & 0 \\ 0 & 0 & 0 & \mathbf{1} & 16 & 3 & -6 & -1 \end{array} \right) \sim \\ &\left( \begin{array}{cccc|cccc} 1 & 0 & 0 & 0 & -3 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 6 & 1 & -2 & 0 \\ 0 & 1 & 0 & 0 & 26 & 4 & -9 & -1 \\ 0 & 0 & 0 & 1 & 16 & 3 & -6 & -1 \end{array} \right) \sim \left( \begin{array}{cccc|cccc} 1 & 0 & 0 & 0 & -3 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 26 & 4 & -9 & -1 \\ 0 & 0 & 1 & 0 & 6 & 1 & -2 & 0 \\ 0 & 0 & 0 & 1 & 16 & 3 & -6 & -1 \end{array} \right) \end{aligned}$$

Este cálculo mostra que o matriz  $\underline{\underline{V}}$  regular, ou seja que  $\underline{v}_1, \underline{v}_2, \underline{v}_3, \underline{v}_4$  formam uma base em  $\mathbb{R}^4$ .

(b) Encontramos as imagens:

$$\begin{aligned} f(\underline{v}_1) &= \underline{v}_1 + \underline{v}_2 = \begin{pmatrix} 1 \\ 2 \\ 4 \\ -2 \end{pmatrix} + \begin{pmatrix} 1 \\ 0 \\ 3 \\ -2 \end{pmatrix} = \begin{pmatrix} 2 \\ 2 \\ 7 \\ -4 \end{pmatrix} \\ f(\underline{v}_2) &= -\underline{v}_1 + \underline{v}_2 = -\begin{pmatrix} 1 \\ 2 \\ 4 \\ -2 \end{pmatrix} + \begin{pmatrix} 1 \\ 0 \\ 3 \\ -2 \end{pmatrix} = \begin{pmatrix} 0 \\ -2 \\ -1 \\ 0 \end{pmatrix} \\ f(\underline{v}_3) &= \underline{v}_3 + \underline{v}_4 = \begin{pmatrix} -1 \\ 1 \\ -3 \\ 5 \end{pmatrix} + \begin{pmatrix} -1 \\ 0 \\ -3 \\ 1 \end{pmatrix} = \begin{pmatrix} -2 \\ 1 \\ -6 \\ 6 \end{pmatrix} \\ f(\underline{v}_4) &= -\underline{v}_3 + \underline{v}_4 = -\begin{pmatrix} -1 \\ 1 \\ -3 \\ 5 \end{pmatrix} + \begin{pmatrix} -1 \\ 0 \\ -3 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ -1 \\ 0 \\ -4 \end{pmatrix} \end{aligned}$$

Isto mostre, que:  $\underline{\underline{A}} \underline{v}_1 = (2, 2, 7, -4)^T$ ,  $\underline{\underline{A}} \underline{v}_2 = (0, -2, -1, 0)^T$ ,  $\underline{\underline{A}} \underline{v}_3 = (-2, 1, -6, 6)^T$ ,  $\underline{\underline{A}} \underline{v}_4 = (0, -1, 0, -4)^T$ . De forma matricial:

$$\begin{aligned} \underline{\underline{A}} \underline{\underline{V}} &= \begin{pmatrix} 2 & 0 & -2 & 0 \\ 2 & -2 & 1 & -1 \\ 7 & -1 & -6 & 0 \\ -4 & 0 & 6 & -4 \end{pmatrix} \Leftrightarrow \underline{\underline{A}} = \begin{pmatrix} 2 & 0 & -2 & 0 \\ 2 & -2 & 1 & -1 \\ 7 & -1 & -6 & 0 \\ -4 & 0 & 6 & -4 \end{pmatrix} \underline{\underline{V}}^{-1} = \\ &\begin{pmatrix} 2 & 0 & -2 & 0 \\ 2 & -2 & 1 & -1 \\ 7 & -1 & -6 & 0 \\ -4 & 0 & 6 & -4 \end{pmatrix} \begin{pmatrix} -3 & 0 & 1 & 0 \\ 26 & 4 & -9 & -1 \\ 6 & 1 & -2 & 0 \\ 16 & 3 & -6 & -1 \end{pmatrix} = \begin{pmatrix} -18 & -2 & 6 & 0 \\ -68 & -10 & 24 & 3 \\ -83 & -10 & 28 & 1 \\ -16 & -6 & 8 & 4 \end{pmatrix} \end{aligned}$$



(c) Procurando as imagens do  $\underline{\mathbf{v}}_1, \dots, \underline{\mathbf{v}}_4$ :

$$\begin{aligned} f(\underline{\mathbf{v}}_1) &= (1, 1, 0, 0)^T \\ f(\underline{\mathbf{v}}_2) &= (-1, 1, 0, 0)^T \\ f(\underline{\mathbf{v}}_3) &= (0, 0, 1, 1)^T \\ f(\underline{\mathbf{v}}_4) &= (0, 0, -1, 1)^T \end{aligned}$$

Assim a matrix procurada é:

$$\underline{\underline{\mathbf{B}}} = \begin{pmatrix} 1 & -1 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & -1 & 1 \end{pmatrix}$$

(d) Temos que:  $\dim U = 2$ , pois  $\underline{\mathbf{v}}_1$  e  $\underline{\mathbf{v}}_2$  são linearmente independentes.  $f(\underline{\mathbf{v}}_1) = \underline{\mathbf{v}}_1 + \underline{\mathbf{v}}_2 \in U$ , e  $f(\underline{\mathbf{v}}_2) = -\underline{\mathbf{v}}_1 + \underline{\mathbf{v}}_2 \in U$ , assim:  $f(U) \subset U$ . Porém as imagens  $f(\underline{\mathbf{v}}_1), f(\underline{\mathbf{v}}_2)$  são linearmente independentes, assim:  $\dim f(U) = 2 = U$ . Juntando:  $f(U) = U$

(e) Obtivemos em item (a) a matriz inversa. Calculamos:

$$\begin{aligned} \underline{\underline{\mathbf{V}}}^{-1} \underline{\underline{\mathbf{A}}} \underline{\underline{\mathbf{V}}} &= \begin{pmatrix} -3 & 0 & 1 & 0 \\ 26 & 4 & -9 & -1 \\ 6 & 1 & -2 & 0 \\ 16 & 3 & -6 & -1 \end{pmatrix} \begin{pmatrix} -18 & -2 & 6 & 0 \\ -68 & -10 & 24 & 3 \\ -83 & -10 & 28 & 1 \\ -16 & -6 & 8 & 4 \end{pmatrix} \begin{pmatrix} 1 & 1 & -1 & -1 \\ 2 & 0 & 1 & 0 \\ 4 & 3 & -3 & -3 \\ -2 & -2 & 5 & 1 \end{pmatrix} = \\ &= \begin{pmatrix} -3 & 0 & 1 & 0 \\ 26 & 4 & -9 & -1 \\ 6 & 1 & -2 & 0 \\ 16 & 3 & -6 & -1 \end{pmatrix} \begin{pmatrix} 2 & 0 & -2 & 0 \\ 2 & -2 & 1 & -1 \\ 7 & -1 & -6 & 0 \\ -4 & 0 & 6 & -4 \end{pmatrix} = \begin{pmatrix} 1 & -1 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 1 & 1 \end{pmatrix} = \underline{\underline{\mathbf{B}}} \end{aligned}$$

QED<sup>1</sup>

**OBS!** Respondendo a prova à lapis, perde-se o direito de revisão da prova. **OBS!**

<sup>1</sup>Quod Erat Demonstrandum: Seja provado!