

# *Formas Quadráticas e Autovalor/Autoveto*

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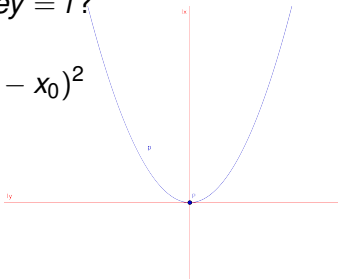
Gods doesn't worry about our mathematical difficulties  
He integrates empirically  
*Albert Einstein*



## Curvas Quadráticas

- Qq é:  $ax^2 + by^2 + 2cxy + dx + ey = f?$
- Parábola:

$$y - y_0 = a(x - x_0)^2$$



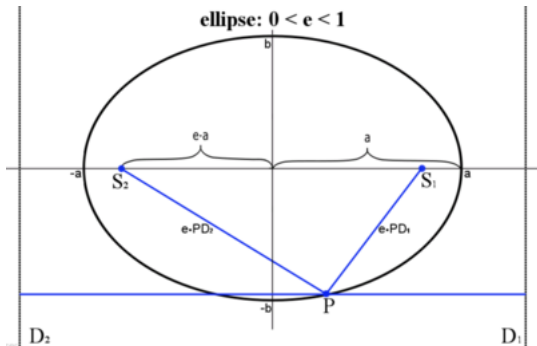
$$y = Ax^2 + Bx + C = A \left[ \left( x + \frac{B}{2A} \right)^2 - \frac{B^2}{4A^2} + \frac{C}{A} \right] \Leftrightarrow$$

$$y + \frac{\Delta}{4A} = A \left( x - \frac{B}{2A} \right)^2 \Rightarrow (x_0, y_0) = \left( -\frac{B}{2A}, -\frac{\Delta}{4A} \right)$$

$$y_0 = Ax_0^2 + C$$

# *Ellipse*

$$\frac{(x - x_0)^2}{a^2} + \frac{(y - y_0)^2}{b^2} = 1$$



## Hiperbole



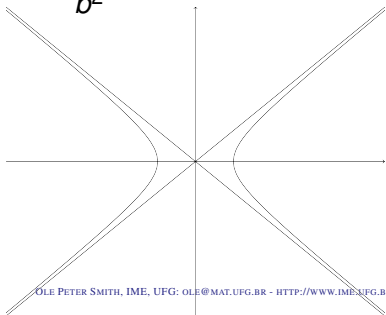
$$\frac{(x - x_0)^2}{a^2} - \frac{(y - y_0)^2}{b^2} = 1$$

Ou:

$$-\frac{(x - x_0)^2}{a^2} + \frac{(y - y_0)^2}{b^2} = 1$$

Assintodas:

$$\frac{(x - x_0)^2}{a^2} - \frac{(y - y_0)^2}{b^2} = 0 \Leftrightarrow y - y_0 = \pm \frac{a}{b}(x - x_0)$$



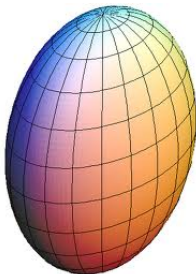
## Superfícies Quadráticas

- Qq é:

$$ax^2 + by^2 + cz^2 + 2dxy + 2exz + 2fyz + gx + hy + iz = j?$$

- Elipsoide:

$$\frac{(x - x_0)^2}{a^2} + \frac{(y - y_0)^2}{b^2} + \frac{(z - z_0)^2}{c^2} = 1$$



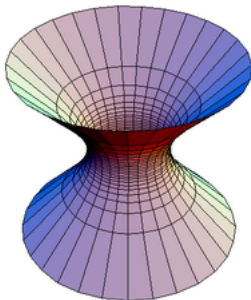
- $z = \text{const}$ : elipses para  $|z - z_0| \leq c$ :

## Superfícies Quadráticas

- Hiperboloide 1 folha:

$$\frac{(x - x_0)^2}{a^2} + \frac{(y - y_0)^2}{b^2} - \frac{(z - z_0)^2}{c^2} = 1$$

- $z = \text{const}$ : elipse,  $x, y = \text{const}$ : Hipérboles

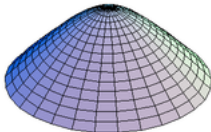
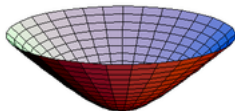


- Gerado por retas!

## Superfícies Quadráticas

- Hiperboloide 2 folhas ( $z=\text{const}$ : elipse,  $x,y=c$ : hipérbole):

$$\frac{(x - x_0)^2}{a^2} - \frac{(y - y_0)^2}{b^2} - \frac{(z - z_0)^2}{c^2} = 1$$

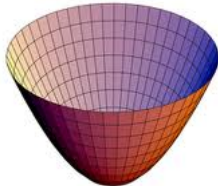


- Gerado por retas!

## Superfícies Quadráticas

- Parabolóide Eliptica ( $z=\text{const}$ : elipse para  $|z - z_0| \leq c$ ):

$$\frac{2(z - z_0)}{c} = \frac{(x - x_0)^2}{a^2} + \frac{(y - y_0)^2}{b^2}$$





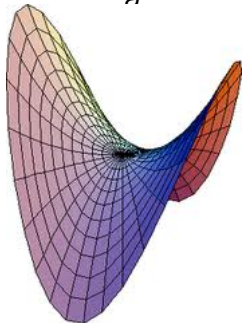
## Superfícies Quadráticas

- Parabolóide Hiperbólica

$$\frac{2(z - z_0)}{c} = \frac{(x - x_0)^2}{a^2} - \frac{(y - y_0)^2}{b^2}$$

Ou:

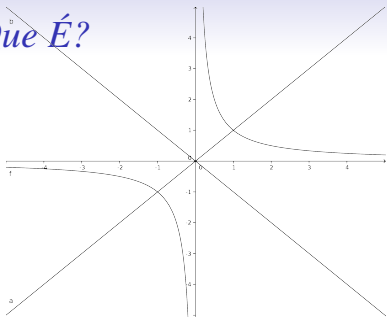
$$\frac{2(z - z_0)}{c} = -\frac{(x - x_0)^2}{a^2} + \frac{(y - y_0)^2}{b^2}$$



- Gerado por retas!

## O Que Que É?

- $xy = 1$
- $y = f(x) = \frac{1}{x}$ ,  $x \in \mathbb{R} - \{0\}$



- Substituição Linear:

$$\begin{pmatrix} x \\ y \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} x' \\ y' \end{pmatrix} =$$

$$\begin{pmatrix} \cos \frac{\pi}{4} & -\sin \frac{\pi}{4} \\ \sin \frac{\pi}{4} & \cos \frac{\pi}{4} \end{pmatrix} \begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} \frac{x' - y'}{\sqrt{2}} \\ \frac{x' + y'}{\sqrt{2}} \end{pmatrix}$$

- $1 = xy = \frac{x' - y'}{\sqrt{2}} \cdot \frac{x' + y'}{\sqrt{2}} = \frac{x'^2 - y'^2}{(\sqrt{2})^2}$

## Formas Quadráticas

- Polinômios Homogêneos, ordem  $n$ :  $P(\lambda x, \lambda y) = \lambda^n P(x, y)$
- No plano:

$$a_{xx}x^2 + 2a_{xy}xy + a_{yy}y^2 = (x \ y) \begin{pmatrix} a_{xx} & a_{xy} \\ a_{xy} & a_{yy} \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \underline{\mathbf{r}}^T \underline{\mathbf{A}} \underline{\mathbf{r}}$$

- No espaço:

$$a_{xx}x^2 + 2a_{xy}xy + 2a_{xz}xz + a_{yy}y^2 + a_{yz}yz + a_{zz}z^2 =$$

$$(x \ y \ z) \begin{pmatrix} a_{xx} & a_{xy} & a_{xz} \\ a_{xy} & a_{yy} & a_{yz} \\ a_{xz} & a_{yz} & a_{zz} \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \underline{\mathbf{r}}^T \underline{\mathbf{A}} \underline{\mathbf{r}}$$

- $\mathbf{A}$  simétricas:  $\mathbf{A}$ <sup>T</sup> =  $\mathbf{A}$

## Sistema Linear Quadrático

- (I) :  $\underline{\underline{\mathbf{A}}} \underline{\underline{\mathbf{v}}} = \underline{\underline{\mathbf{b}}}$
- Se  $\det \underline{\underline{\mathbf{A}}} \neq 0$ ,  $\exists! \underline{\underline{\mathbf{A}}}^{-1}$  :  $\underline{\underline{\mathbf{A}}} \underline{\underline{\mathbf{A}}}^{-1} = \underline{\underline{\mathbf{A}}}^{-1} \underline{\underline{\mathbf{A}}} = \underline{\underline{\mathbf{I}}}$ .
- Assim:  $\underline{\underline{\mathbf{v}}} = \underline{\underline{\mathbf{A}}}^{-1} \underline{\underline{\mathbf{b}}}$ .
- Matriz Total:  $\underline{\underline{\mathbf{T}}} = (\underline{\underline{\mathbf{A}}} \mid \underline{\underline{\mathbf{b}}})$ .
- Posto  $\rho$ : Ordem do maior subdeterminante sendo  $\neq 0$ .
- $\rho \leq n$ . Se  $\det \underline{\underline{\mathbf{A}}} \neq 0$ :  $\rho = n$ .
- (I) tem solução se e só se:  $\rho = \rho_{\underline{\underline{\mathbf{A}}}} = \rho_{\underline{\underline{\mathbf{T}}}}$ .
- $S = \underline{\underline{\mathbf{v}}}_0 + \sum_{i=1}^{n-\rho} t_i \underline{\underline{\mathbf{v}}}_i$ ,  $t_i \in \mathbb{R}$ : SCSiH=SPSiH+SCSH.
- Uma  $(n - \rho)$ -infinidade de soluções:  $\dim S = n - \rho$ .

## Aplicação Linear, $f : \mathbb{R}^n \rightarrow \mathbb{R}^n$

$$f(\underline{\mathbf{v}}) = \underline{\mathbf{A}} \underline{\mathbf{v}}$$

- $\mathbf{A}$  matriz coluna:

- $\underline{\mathbf{a}}_i = f(\underline{\mathbf{e}}_i)$ : 
$$\underline{\mathbf{A}} = \left( \begin{array}{c|c|c|c} & & & \\ \underline{\mathbf{a}}_1 & \underline{\mathbf{a}}_2 & \cdots & \underline{\mathbf{a}}_n \\ & & & \end{array} \right)$$

$$f(\underline{\mathbf{e}}_i) = \left( \begin{array}{c|c|c|c} & & & \\ \underline{\mathbf{a}}_1 & \underline{\mathbf{a}}_2 & \cdots & \underline{\mathbf{a}}_n \\ & & & \end{array} \right) \begin{pmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{pmatrix} \leftarrow i = \underline{\mathbf{a}}_i$$

- $Im(f) = ger(\underline{\mathbf{a}}_1, \dots, \underline{\mathbf{a}}_n) = \{ \underline{\mathbf{x}} \in \mathbb{R}^n \mid \underline{\mathbf{x}} = c_1 \underline{\mathbf{a}}_1 + \dots + c_n \underline{\mathbf{a}}_n \}$ .
- $\dim Im(f) = \dim ger(\underline{\mathbf{a}}_1, \dots, \underline{\mathbf{a}}_n) = \rho_{\underline{\mathbf{A}}}$ .



## Autovetor/Autovalor

- Por quais  $\lambda \in \mathbb{R}$  tem soluções não-triviais,  $\underline{\mathbf{v}} \neq \underline{\mathbf{0}}$ :

$$\underline{\mathbf{A}} \underline{\mathbf{v}} = \lambda \underline{\mathbf{v}} = \lambda \underline{\mathbf{I}} \underline{\mathbf{v}} \quad \Leftrightarrow \quad (\underline{\mathbf{A}} - \lambda \underline{\mathbf{I}}) \underline{\mathbf{x}} = \underline{\mathbf{0}}$$

- Se  $\underline{\mathbf{A}}_{\lambda} = \underline{\mathbf{A}} - \lambda \underline{\mathbf{I}}$  regular:

$$\det \underline{\mathbf{A}}_{\lambda} = \det (\underline{\mathbf{A}} - \lambda \underline{\mathbf{I}}) \neq 0,$$

solução única:  $\underline{\mathbf{v}} = \underline{\mathbf{A}}_{\lambda}^{-1} \underline{\mathbf{0}} = \underline{\mathbf{0}}$ . Trivialmente!!!!

- Soluções não-triviais, see  $\lambda$  raiz no *Polinômio Caraterístico*:

$$P_n(\lambda) = \det (\underline{\mathbf{A}} - \lambda \underline{\mathbf{I}}) = 0$$

## Polinômio Característico I

$$P_n(\lambda) = \det(\underline{\underline{\mathbf{A}}} - \lambda \underline{\underline{\mathbf{I}}}) = \begin{vmatrix} a_{11} - \lambda & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} - \lambda & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} - \lambda \end{vmatrix} =$$

$$(-1)^n \lambda^n - (-1)^n \lambda^{n-1} \text{Tr}(\underline{\underline{\mathbf{A}}}) + \cdots + \det \underline{\underline{\mathbf{A}}}$$

- Polinômio de grau  $n$  com coeficientes reais.
- Máx.  $n$  raízes reais.
- Número par de raízes complexas.
- Grau ímpar: Mín. uma raíz real.
- Raízes:

$$P_n(\lambda) = (\lambda_1 - \lambda) \cdots (\lambda_n - \lambda) =$$

$$P_n(\lambda) = (-1)^n \lambda^n - (-1)^n \lambda^{n-1} \sum_{i=1}^n \lambda_i + \cdots + \prod_{i=1}^n \lambda_i$$



## Polinômio Carareístico II

$$P(\lambda) = (-1)^n \lambda^n - (-1)^n \lambda^{n-1} \text{Tr}(\underline{\underline{\mathbf{A}}}) + \dots + \det \underline{\underline{\mathbf{A}}}$$

$$P(\lambda) = (-1)^n \lambda^n - (-1)^n \lambda^{n-1} \sum_{i=1}^n \lambda_i + \dots + \prod_{i=1}^n \lambda_i$$

- $\sum_{i=1}^n \lambda_i = \text{Tr}(\underline{\underline{\mathbf{A}}}) = a_{11} + \dots + a_{nn}.$
- $\prod_{i=1}^n \lambda_i = \det \underline{\underline{\mathbf{A}}}.$



## Auto-espços I

$$S_\lambda = \{\underline{\mathbf{v}} \in \mathbb{R}^n \mid \underline{\mathbf{A}} \underline{\mathbf{v}} = \lambda \underline{\mathbf{v}}\}$$

- Espaços vetoriais:

$$(i) : \underline{\mathbf{v}} \in S_\lambda, c \in \mathbb{R} \Rightarrow c \underline{\mathbf{v}} \in S_\lambda$$

$$(ii) : \underline{\mathbf{v}}, \underline{\mathbf{w}} \in S_\lambda \Rightarrow \underline{\mathbf{v}} + \underline{\mathbf{w}} \in S_\lambda$$

- $P(\lambda) \neq 0$ :  $S_\lambda = \{\underline{\mathbf{0}}\}$ .
- $P(\lambda) = 0$ :  $1 \leq \dim S_\lambda \leq n$ .
- $\bigcup_{\lambda_i \in \mathbb{R}} S_{\lambda_i} \subset \mathbb{R}^n$ .

## Auto-espacos II

- *Teorema:* Autovetores de autovalores diferentes são linearmente independentes (LI).
- Dado  $\lambda_1 \neq \lambda_2$ , e  $\underline{v}_1, \underline{v}_2 \neq \underline{0}$ :

$$\underline{A} \underline{v}_1 = \lambda_1 \underline{v}_1 \quad \wedge \quad \underline{A} \underline{v}_2 = \lambda_2 \underline{v}_2$$

- Suponha  $\underline{v}_1, \underline{v}_2$  linearmente dependentes (LD):

$$\underline{v}_1 = c \underline{v}_2 \Rightarrow \underline{A} c \underline{v}_1 = \lambda_2 c \underline{v}_1 \Leftrightarrow$$

$$\underline{A} \underline{v}_1 = \lambda_2 \underline{v}_1 \Leftrightarrow \lambda_1 \underline{v}_1 = \lambda_2 \underline{v}_1 \Leftrightarrow$$

$$(\lambda_1 - \lambda_2) \underline{v}_1 = \underline{0} \Leftrightarrow \lambda_1 = \lambda_2 \vee \underline{v}_1 = \underline{0}$$

**Absurdo!**

- $\lambda_1 \neq \lambda_2: S_{\lambda_1} \cap S_{\lambda_2} = \{\underline{0}\}$

## Auto-espacos III

- 'Perder AVs':
  - $\lambda_i \in \mathbb{C} - \mathbb{R}: \bar{\lambda}_i \neq \lambda_i$ ;
  - $\dim S_{\lambda_i} < \rho_{\lambda_i}$ .
- $\dim \bigcup_{\lambda_i \in \mathbb{R}} S_{\lambda_i} = n \Rightarrow \exists$  base de autovetores!
- Se  $\exists$  base de autovetores:  $\underline{\mathbf{v}}_1, \dots, \underline{\mathbf{v}}_n$ :

$$\underline{\mathbf{A}} \underline{\mathbf{v}}_j = \lambda_j \underline{\mathbf{v}}_j = [0, \dots, \lambda_j, \dots, 0] \underline{\mathbf{v}}_j^T$$

## Matrizes Simétricas

- Teorema: Se  $\underline{\underline{\mathbf{A}}}$  é simétrica, todos os autovalores são reais.
- Meu Pai criou esse Matemática meeeeeesmo....
- Lembre-se:  $(\underline{\underline{\mathbf{A}}}\underline{\underline{\mathbf{B}}})^T = \underline{\underline{\mathbf{B}}}^T \underline{\underline{\mathbf{A}}}^T$ ,  $\overline{\underline{\underline{\mathbf{A}}}\underline{\underline{\mathbf{B}}}} = \overline{\underline{\underline{\mathbf{A}}}}\overline{\underline{\underline{\mathbf{B}}}}$ .
- E em  $\mathbb{C}$ :  $\underline{\underline{\mathbf{v}}}\cdot\underline{\underline{\mathbf{w}}} = \overline{\underline{\underline{\mathbf{v}}}}^T \underline{\underline{\mathbf{w}}}$ , (garantindo:  $|\underline{\underline{\mathbf{v}}}|^2 \geq 0$ ).
- $\rightarrow$ :  $\lambda \in \mathbb{R} \Rightarrow \underline{\underline{\mathbf{v}}} \in \mathbb{R}^n!$
- Suponha:  $\lambda \notin \mathbb{R}$  ( $\bar{\lambda} \neq \lambda$ ) e  $\underline{\underline{\mathbf{v}}} \neq \underline{\underline{\mathbf{0}}}$ :

$$\underline{\underline{\mathbf{A}}}\underline{\underline{\mathbf{v}}} = \lambda\underline{\underline{\mathbf{v}}} \quad \Rightarrow \quad \overline{\underline{\underline{\mathbf{v}}}}^T \underline{\underline{\mathbf{A}}}\underline{\underline{\mathbf{v}}} = \lambda|\underline{\underline{\mathbf{v}}}|^2 \in \mathbb{C} \quad \Rightarrow \quad (\lambda|\underline{\underline{\mathbf{v}}}|^2)^T = \lambda|\underline{\underline{\mathbf{v}}}|^2$$

- $\bar{\lambda}|\underline{\underline{\mathbf{v}}}|^2 = (\bar{\lambda}|\underline{\underline{\mathbf{v}}}|^2)^T = (\overline{\lambda|\underline{\underline{\mathbf{v}}}|^2})^T = (\overline{\overline{\underline{\underline{\mathbf{v}}}}^T \underline{\underline{\mathbf{A}}}\underline{\underline{\mathbf{v}}}})^T = (\underline{\underline{\mathbf{v}}}^T \underline{\underline{\mathbf{A}}}\overline{\underline{\underline{\mathbf{v}}}})^T =$   
 $(\underline{\underline{\mathbf{v}}}^T \underline{\underline{\mathbf{A}}}\overline{\underline{\underline{\mathbf{v}}}})^T = \overline{\underline{\underline{\mathbf{v}}}}^T \underline{\underline{\mathbf{A}}}\underline{\underline{\mathbf{v}}} = \lambda|\underline{\underline{\mathbf{v}}}|^2 \Leftrightarrow (\lambda - \bar{\lambda})|\underline{\underline{\mathbf{v}}}|^2 = 0 \Leftrightarrow$   
 $\lambda = \bar{\lambda} \Leftrightarrow \lambda \in \mathbb{R} \quad \square$

## Matrizes Simétricas: $\underline{\underline{\mathbf{A}}} = \underline{\underline{\mathbf{A}}}^T$

- *Teorema:* Autovetores de autovalores diferentes,  $\tilde{\mathbf{v}}$  ortogonais.
- Meu Pai éeeeeeeeeeeeeee divino!
- Suponha:  $\underline{\underline{\mathbf{A}}} \underline{\underline{\mathbf{v}}}_1 = \lambda_1 \underline{\underline{\mathbf{v}}}_1$  e  $\underline{\underline{\mathbf{A}}} \underline{\underline{\mathbf{v}}}_2 = \lambda_2 \underline{\underline{\mathbf{v}}}_2$  com  $\lambda_1 \neq \lambda_2$ .
- $\underline{\underline{\mathbf{v}}}_2^T \underline{\underline{\mathbf{A}}} \underline{\underline{\mathbf{v}}}_1 = \underline{\underline{\mathbf{v}}}_2^T \lambda_1 \underline{\underline{\mathbf{v}}}_1 = \lambda_1 \underline{\underline{\mathbf{v}}}_1 \cdot \underline{\underline{\mathbf{v}}}_2$ .
- $\underline{\underline{\mathbf{v}}}_1^T \underline{\underline{\mathbf{A}}} \underline{\underline{\mathbf{v}}}_2 = \underline{\underline{\mathbf{v}}}_1^T \lambda_2 \underline{\underline{\mathbf{v}}}_2 = \lambda_2 \underline{\underline{\mathbf{v}}}_1 \cdot \underline{\underline{\mathbf{v}}}_2$ .
- Por ser um número:  $\underline{\underline{\mathbf{v}}}_1^T \underline{\underline{\mathbf{A}}} \underline{\underline{\mathbf{v}}}_2 = (\underline{\underline{\mathbf{v}}}_1^T \underline{\underline{\mathbf{A}}} \underline{\underline{\mathbf{v}}}_2)^T = \underline{\underline{\mathbf{v}}}_2^T \underline{\underline{\mathbf{A}}} \underline{\underline{\mathbf{v}}}_1$
- Conclusão:  
 $\lambda_1 \underline{\underline{\mathbf{v}}}_1 \cdot \underline{\underline{\mathbf{v}}}_2 = \lambda_2 \underline{\underline{\mathbf{v}}}_1 \cdot \underline{\underline{\mathbf{v}}}_2 \Leftrightarrow (\lambda_1 - \lambda_2) \underline{\underline{\mathbf{v}}}_1 \cdot \underline{\underline{\mathbf{v}}}_2 = 0 \Leftrightarrow \underline{\underline{\mathbf{v}}}_1 \cdot \underline{\underline{\mathbf{v}}}_2 = 0$
- *Teorema:* Se  $\lambda_i$  raiz de ordem  $\rho_i$  em  $P_n(\lambda)$ :  $\dim S_{\lambda_i} = \rho_i$ .
- Podemos ortogonalizar espaços (Gram-Schmidt)!

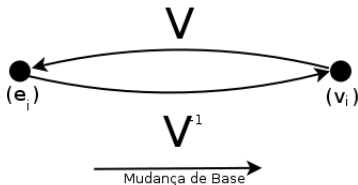
## Mudança de Base I

- Base novo:  $(\underline{\mathbf{v}}_1, \dots, \underline{\mathbf{v}}_n)$ , formamos:

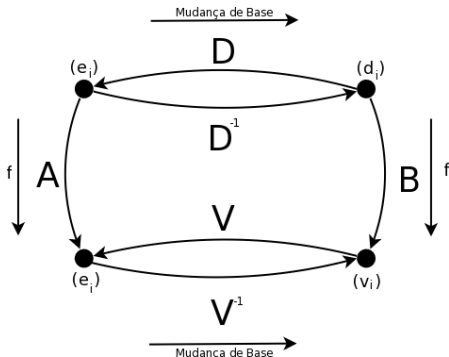
$$\underline{\underline{\mathbf{V}}} = \left( \begin{array}{c|ccc|c} & & & & \\ & & & & \\ & \underline{\mathbf{v}}_1 & \cdots & \underline{\mathbf{v}}_n & \\ & & & & \end{array} \right)$$

- Coordenados antigos,  $\underline{\mathbf{v}}$ , e novos,  $\underline{\mathbf{v}}'$ .

$$\underline{\mathbf{v}} = \underline{\underline{\mathbf{V}}} \underline{\mathbf{v}}' \quad \Leftrightarrow \quad \underline{\mathbf{v}}' = \underline{\underline{\mathbf{V}}}^{-1} \underline{\mathbf{v}}$$



## Mudança de Base II



- $\underline{\underline{D}} = \underline{\underline{V}}$
- $\underline{\underline{B}} = \underline{\underline{V}}^{-1} \underline{\underline{A}} \underline{\underline{V}}$ .
- $\underline{\underline{A}}$  e  $\underline{\underline{B}}$  similares:  $\underline{\underline{A}} \sim \underline{\underline{B}} \Leftrightarrow \exists \underline{\underline{V}} : \underline{\underline{B}} = \underline{\underline{V}}^{-1} \underline{\underline{A}} \underline{\underline{V}}$ .
- Mesma aplicação linear/forma quadrática/curva em bases diferentes.

## Matrizes Similares I

- Similaridade ( $\sim$ ) Relação de Equivalência:
- Reflexiva: (sou meu próprio amigo):

$$\underline{\underline{\mathbf{A}}} = \underline{\underline{\mathbf{I}}}^{-1} \underline{\underline{\mathbf{A}}} \underline{\underline{\mathbf{I}}}$$

- Simétrica (sou amigo do meus amigo e vice-versa).

$$\underline{\underline{\mathbf{B}}} = \underline{\underline{\mathbf{V}}}^{-1} \underline{\underline{\mathbf{A}}} \underline{\underline{\mathbf{V}}} \Leftrightarrow \underline{\underline{\mathbf{A}}} = \underline{\underline{\mathbf{V}}} \underline{\underline{\mathbf{A}}} \underline{\underline{\mathbf{V}}}^{-1}$$

- Transitiva (sou amigo dos amigos dos meus amigos).

$$\underline{\underline{\mathbf{B}}} = \underline{\underline{\mathbf{V}}}^{-1} \underline{\underline{\mathbf{A}}} \underline{\underline{\mathbf{V}}} \wedge \underline{\underline{\mathbf{C}}} = \underline{\underline{\mathbf{W}}}^{-1} \underline{\underline{\mathbf{B}}} \underline{\underline{\mathbf{W}}} \Rightarrow$$

$$\underline{\underline{\mathbf{C}}} = \underline{\underline{\mathbf{W}}}^{-1} \underline{\underline{\mathbf{B}}} \underline{\underline{\mathbf{W}}} = \underline{\underline{\mathbf{W}}}^{-1} (\underline{\underline{\mathbf{V}}}^{-1} \underline{\underline{\mathbf{A}}} \underline{\underline{\mathbf{V}}}) \underline{\underline{\mathbf{W}}} =$$

$$(\underline{\underline{\mathbf{W}}}^{-1} \underline{\underline{\mathbf{V}}}^{-1}) \underline{\underline{\mathbf{A}}} (\underline{\underline{\mathbf{V}}} \underline{\underline{\mathbf{W}}}) = (\underline{\underline{\mathbf{V}}} \underline{\underline{\mathbf{W}}})^{-1} \underline{\underline{\mathbf{A}}} (\underline{\underline{\mathbf{V}}} \underline{\underline{\mathbf{W}}})$$



## Matrizes Similares II

- Matrizes Similares tem mesmo Determinante:

$$\det \underline{\underline{\mathbf{B}}} = \det \left( \underline{\underline{\mathbf{V}}}^{-1} \underline{\underline{\mathbf{A}}} \underline{\underline{\mathbf{V}}} \right) = \det \left( \underline{\underline{\mathbf{V}}}^{-1} \right) \det \underline{\underline{\mathbf{A}}} \det \underline{\underline{\mathbf{V}}} =$$
$$\left( \det \underline{\underline{\mathbf{V}}} \right)^{-1} \det \underline{\underline{\mathbf{A}}} \det \underline{\underline{\mathbf{V}}} = \det \underline{\underline{\mathbf{A}}}$$

- Matrizes Similares tem mesmo Polinômio Característico:

$$\det \left( \underline{\underline{\mathbf{B}}} - \lambda \underline{\underline{\mathbf{I}}} \right) = \det \left( \underline{\underline{\mathbf{V}}}^{-1} \underline{\underline{\mathbf{A}}} \underline{\underline{\mathbf{V}}} - \lambda \underline{\underline{\mathbf{I}}} \right) =$$
$$\det \left( \underline{\underline{\mathbf{V}}}^{-1} \underline{\underline{\mathbf{A}}} \underline{\underline{\mathbf{V}}} - \lambda \underline{\underline{\mathbf{V}}}^{-1} \underline{\underline{\mathbf{I}}} \underline{\underline{\mathbf{V}}} \right) = \det \left( \underline{\underline{\mathbf{V}}}^{-1} \left( \underline{\underline{\mathbf{A}}} - \lambda \underline{\underline{\mathbf{I}}} \right) \underline{\underline{\mathbf{V}}} \right) =$$
$$\det \left( \underline{\underline{\mathbf{A}}} - \lambda \underline{\underline{\mathbf{I}}} \right)$$

## Matrizes Similares III

- Matrizes Similares tem mesmo Autovalores.
- Os autovalores  $\tilde{\lambda}$  *Invariantes* de uma mudança de Base.
- Os coeficientes do Polinômio Caraterístico  $\tilde{p}$  *Invariantes*.
- Matrizes Similares tem mesmo Traço:  $\underline{\underline{Tr\mathbf{A}}} = \sum_i \lambda_i$ .
- Matrizes Similares  $\tilde{A}$ ... Similares.

## Base de Autovetores

- Em base  $\underline{\mathbf{v}}_1, \dots, \underline{\mathbf{v}}_n$ :

$$\lambda_i \underline{\mathbf{v}}_i = [0, \dots, \overset{i}{\downarrow} \lambda_i, \dots, 0]_{\underline{\mathbf{v}}}^T$$

- B** diagonal:

$$\underline{\underline{\mathbf{B}}} = \begin{pmatrix} \left. \begin{array}{c} | \\ f(\underline{\mathbf{v}}_1) \\ | \end{array} \right. & \left. \begin{array}{c} | \\ f(\underline{\mathbf{v}}_2) \\ | \end{array} \right. & \cdots & \left. \begin{array}{c} | \\ f(\underline{\mathbf{v}}_n) \\ | \end{array} \right. \end{pmatrix} =$$
$$\begin{pmatrix} \left. \begin{array}{c} | \\ \lambda_1 \underline{\mathbf{v}}_1 \\ | \end{array} \right. & \left. \begin{array}{c} | \\ \lambda_2 \underline{\mathbf{v}}_2 \\ | \end{array} \right. & \cdots & \left. \begin{array}{c} | \\ \lambda_n \underline{\mathbf{v}}_n \\ | \end{array} \right. \end{pmatrix} = \begin{pmatrix} \lambda_1 & 0 & \cdots & 0 \\ 0 & \lambda_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \lambda_n \end{pmatrix}$$

- Teorema:** Se **A** = **A**<sup>T</sup>, existe um base,  $\underline{\mathbf{v}}_1, \dots, \underline{\mathbf{v}}_n$ , ortonormal:  $\underline{\mathbf{v}}_i \cdot \underline{\mathbf{v}}_j = \delta_{ij}$  de autovetores: **A**  $\underline{\mathbf{v}}_i = \lambda_i \underline{\mathbf{v}}_i$ .

## Matrizes Ortogonais

Base Ortonormal em Colunas:

- $$\underline{\underline{\mathbf{V}}} = \left( \begin{array}{c|c|c|c} | & | & \cdots & | \\ \mathbf{v}_1 & \mathbf{v}_2 & & \mathbf{v}_n \\ | & | & & | \end{array} \right) \Leftrightarrow \underline{\underline{\mathbf{V}}}^T = \left( \begin{array}{c|c} - & \mathbf{v}_1 & - \\ - & \mathbf{v}_2 & - \\ & \vdots & \\ - & \mathbf{v}_n & - \end{array} \right)$$

- $$\underline{\underline{\mathbf{V}}}^T \underline{\underline{\mathbf{V}}} = \left( \begin{array}{c|c|c} - & \mathbf{v}_1 & - \\ - & \mathbf{v}_2 & - \\ & \vdots & \\ - & \mathbf{v}_n & - \end{array} \right) \left( \begin{array}{c|c|c|c} | & | & \cdots & | \\ \mathbf{v}_1 & \mathbf{v}_2 & & \mathbf{v}_n \\ | & | & & | \end{array} \right)$$

$$\left( \begin{array}{cccc} \mathbf{v}_1 \cdot \mathbf{v}_1 & \mathbf{v}_1 \cdot \mathbf{v}_2 & \cdots & \mathbf{v}_1 \cdot \mathbf{v}_n \\ \mathbf{v}_2 \cdot \mathbf{v}_1 & \mathbf{v}_2 \cdot \mathbf{v}_2 & \cdots & \mathbf{v}_2 \cdot \mathbf{v}_n \\ \vdots & \vdots & \ddots & \vdots \\ \mathbf{v}_n \cdot \mathbf{v}_1 & \mathbf{v}_n \cdot \mathbf{v}_2 & \cdots & \mathbf{v}_n \cdot \mathbf{v}_n \end{array} \right) = (\mathbf{v}_i \cdot \mathbf{v}_j) = (\delta_{ij}) = \underline{\underline{\mathbf{I}}} \Leftrightarrow$$

$$\underline{\underline{\mathbf{V}}}^{-1} = \underline{\underline{\mathbf{V}}}^T$$

- $(\det \underline{\underline{\mathbf{V}}})^2 = \det \underline{\underline{\mathbf{I}}} = 1 \Leftrightarrow \det \underline{\underline{\mathbf{V}}} = \pm 1.$

## Caso Complexo

- **A** Hermitiano: **A**<sup>T</sup> = **A**<sup>¯</sup>.
- Hermitiano ⇒ autovalores reais.
- Hermitiano ⇒ autovetores ortogonalizáveis.
- **U** Unitário: **U**<sup>-1</sup> = **U**<sup>¯T</sup>.

## Base de Autovetores Ortonormais

$$\begin{aligned}
 \bullet \quad \underline{\underline{\mathbf{B}}} &= \underline{\underline{\mathbf{V}}}^{-1} \underline{\underline{\mathbf{A}}} \underline{\underline{\mathbf{V}}} = \underline{\underline{\mathbf{V}}}^T \underline{\underline{\mathbf{A}}} \underline{\underline{\mathbf{V}}} = \\
 &\begin{pmatrix} - & \underline{\underline{\mathbf{v}}}_1 & - \\ - & \underline{\underline{\mathbf{v}}}_2 & - \\ & \vdots & \\ - & \underline{\underline{\mathbf{v}}}_n & - \end{pmatrix} \begin{pmatrix} | & & | & & | \\ \lambda_1 \underline{\underline{\mathbf{v}}}_1 & & \lambda_2 \underline{\underline{\mathbf{v}}}_2 & \cdots & \lambda_n \underline{\underline{\mathbf{v}}}_n \\ | & & | & & | \end{pmatrix} = \\
 &\begin{pmatrix} - & \underline{\underline{\mathbf{v}}}_1 & - \\ - & \underline{\underline{\mathbf{v}}}_2 & - \\ & \vdots & \\ - & \underline{\underline{\mathbf{v}}}_n & - \end{pmatrix} \underline{\underline{\mathbf{A}}} \begin{pmatrix} | & & | & & | \\ \underline{\underline{\mathbf{v}}}_1 & & \underline{\underline{\mathbf{v}}}_2 & \cdots & \underline{\underline{\mathbf{v}}}_n \\ | & & | & & | \end{pmatrix} = \\
 &\begin{pmatrix} \lambda_1 \underline{\underline{\mathbf{v}}}_1 \cdot \underline{\underline{\mathbf{v}}}_1 & \lambda_2 \underline{\underline{\mathbf{v}}}_1 \cdot \underline{\underline{\mathbf{v}}}_2 & \cdots & \lambda_n \underline{\underline{\mathbf{v}}}_1 \cdot \underline{\underline{\mathbf{v}}}_n \\ \lambda_1 \underline{\underline{\mathbf{v}}}_2 \cdot \underline{\underline{\mathbf{v}}}_1 & \lambda_2 \underline{\underline{\mathbf{v}}}_2 \cdot \underline{\underline{\mathbf{v}}}_2 & \cdots & \lambda_n \underline{\underline{\mathbf{v}}}_2 \cdot \underline{\underline{\mathbf{v}}}_n \\ \vdots & \vdots & & \vdots \\ \lambda_1 \underline{\underline{\mathbf{v}}}_n \cdot \underline{\underline{\mathbf{v}}}_1 & \lambda_2 \underline{\underline{\mathbf{v}}}_n \cdot \underline{\underline{\mathbf{v}}}_2 & \cdots & \lambda_n \underline{\underline{\mathbf{v}}}_n \cdot \underline{\underline{\mathbf{v}}}_n \end{pmatrix} = (\lambda_i \delta_{ij})
 \end{aligned}$$

## Base de Autovetores Ortonormais

- $F(x, y) = \underline{\mathbf{r}}^T \underline{\mathbf{A}} \underline{\mathbf{r}} = \underline{\mathbf{r}}'^T \underline{\mathbf{B}} \underline{\mathbf{r}}' = \lambda_1 x'^2 + \lambda_2 y'^2.$   
 $F(x, y, z) = \lambda_1 x'^2 + \lambda_2 y'^2 + \lambda_3 z'^2.$
- Termos 'mistos' Eliminados!!!!

Problemas resolvemos na hora.

As Milagres demoram mais um pouco...

- $\underline{\mathbf{r}} = \underline{\mathbf{V}} \underline{\mathbf{r}}' \Leftrightarrow \underline{\mathbf{r}}' = \underline{\mathbf{V}}^T \underline{\mathbf{r}}.$
- $j =$

$$\overbrace{ax^2 + by^2 + cz^2 + 2dxy + 2exz + 2fyz}^Q + \overbrace{gx + hy + iz}^L =$$

$$\underline{\mathbf{r}}^T \underline{\mathbf{A}} \underline{\mathbf{r}} + \underline{\mathbf{b}}^T \underline{\mathbf{r}} = (\underline{\mathbf{V}} \underline{\mathbf{r}}')^T \underline{\mathbf{A}} (\underline{\mathbf{V}} \underline{\mathbf{r}}') + \underline{\mathbf{b}}^T (\underline{\mathbf{V}} \underline{\mathbf{r}}') =$$

$$\underline{\mathbf{r}}'^T (\underline{\mathbf{V}}^T \underline{\mathbf{A}} \underline{\mathbf{V}}) \underline{\mathbf{r}} + (\underline{\mathbf{V}}^T \underline{\mathbf{b}})^T \underline{\mathbf{r}}' = \underline{\mathbf{r}}'^T \underline{\mathbf{B}} \underline{\mathbf{r}}' + \underline{\mathbf{b}}'^T \underline{\mathbf{r}}'$$

## Caso $n = 2$ : Curvas Quadráticas

- $\underline{\underline{\mathbf{A}}} = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}$

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$$\det(\underline{\underline{\mathbf{A}}} - \lambda \underline{\underline{\mathbf{I}}}) = \begin{vmatrix} a_{11} - \lambda & a_{12} \\ a_{21} & a_{22} - \lambda \end{vmatrix} = (a_{11} - \lambda)(a_{22} - \lambda) - a_{12}a_{21} =$$

$$\lambda^2 - (a_{11} + a_{22})\lambda + a_{11}a_{22} - a_{12}a_{21} = \lambda^2 - \text{Tr}\underline{\underline{\mathbf{A}}}\lambda + \det\underline{\underline{\mathbf{A}}}$$

- $\Delta = (a_{11} + a_{22})^2 - 4(a_{11}a_{22} - a_{12}a_{21}) = (a_{11} - a_{22})^2 + 4a_{12}a_{21}$

- $\underline{\underline{\mathbf{A}}} = \underline{\underline{\mathbf{A}}}^T$ :

- $\Delta = (a_{11} - a_{22})^2 + 4a_{12}^2 \geq 0$ ;

- $\Delta = 0 \Leftrightarrow a_{11} = a_{22} := a \wedge a_{12} = 0 \Leftrightarrow \underline{\underline{\mathbf{A}}} = a \underline{\underline{\mathbf{I}}}$ : Já diagonal!

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$$\lambda_{\pm} = \frac{a_{11} + a_{22} \pm \sqrt{\Delta}}{2}$$



$$\lambda = \lambda_{\pm} = \frac{a_{11} + a_{22} \pm \sqrt{\Delta}}{2}$$

$$\begin{aligned} \underline{\underline{\mathbf{A}}} - \lambda_{\pm} \underline{\underline{\mathbf{I}}} &= \begin{pmatrix} a_{11} - \lambda_{\pm} & a_{12} \\ a_{21} & a_{22} - \lambda_{\pm} \end{pmatrix} = \\ &\begin{pmatrix} a_{11} - \frac{a_{11} + a_{22} \mp \sqrt{\Delta}}{2} & a_{12} \\ a_{21} & a_{22} - \frac{a_{11} + a_{22} \mp \sqrt{\Delta}}{2} \end{pmatrix} \sim \\ &\begin{pmatrix} a_{11} - a_{22} \mp \sqrt{\Delta} & 2a_{12} \\ 2a_{21} & a_{22} - a_{11} \mp \sqrt{\Delta} \end{pmatrix} \sim \\ &\begin{pmatrix} a_{11} - a_{22} \mp \sqrt{\Delta} & 2a_{12} \\ 0 & 0 \end{pmatrix} \underline{\underline{\mathbf{x}}} = \underline{\underline{\mathbf{0}}} \Leftrightarrow \\ &x_1(a_{11} - a_{22} \mp \sqrt{\Delta}) + 2x_2 2a_{12} = 0 \end{aligned}$$

$$\lambda = \lambda_{\pm} = \frac{a_{11} + a_{22} \pm \sqrt{\Delta}}{2}, \text{ cont.:}$$

- Solução completa;  $t, t' \in \mathbb{R}$ :

$$\underline{\mathbf{x}}_{\pm} = t \underbrace{\begin{pmatrix} -2a_{12} \\ a_{11} - a_{22} \mp \sqrt{\Delta} \end{pmatrix}}_{\underline{\mathbf{v}}_{\pm}} = t' \underbrace{\begin{pmatrix} a_{22} - a_{11} \mp \sqrt{\Delta} \\ -2a_{21} \end{pmatrix}}_{\underline{\mathbf{w}}_{\pm}}$$

- $\underline{\mathbf{v}}_{+} \parallel \underline{\mathbf{w}}_{+} \wedge \underline{\mathbf{v}}_{-} \parallel \underline{\mathbf{w}}_{-}$ .

- $\underline{\mathbf{v}}_{+} \cdot \underline{\mathbf{v}}_{-} =$   
 $4a_{12}^2 + (a_{11} - a_{22} + \sqrt{\Delta})(a_{11} - a_{22} - \sqrt{\Delta})$

$$\begin{aligned} 4a_{12}^2 + (a_{11} - a_{22})^2 - \Delta &= 4a_{12}^2 + (a_{11} - a_{22})^2 - ((a_{11} - a_{22})^2 + 4a_{12}a_{21}) \\ &= 4a_{12}(a_{12} - a_{21}) = -\underline{\mathbf{v}}_{-} \cdot \underline{\mathbf{w}}_{+} \end{aligned}$$

- Se  $a_{12} = a_{21}$ :  $\underline{\mathbf{v}}_{+} \perp \underline{\mathbf{v}}_{-} \wedge \underline{\mathbf{w}}_{+} \perp \underline{\mathbf{w}}_{-}$ .

- $\hat{\underline{\mathbf{v}}}_{\pm} = \underline{\mathbf{w}}_{\mp}$ .

$$\lambda = \lambda_{\pm} = \frac{a_{11} + a_{22} \pm \sqrt{\Delta}}{2}, \text{ cont.:}$$

- Escolhemos:

$$\underline{\mathbf{v}}_1 = \underline{\mathbf{v}}_+ = \begin{pmatrix} -2a_{12} \\ a_{11} - a_{22} \mp \sqrt{\Delta} \end{pmatrix}, \quad \tilde{\underline{\mathbf{v}}}_1 = \frac{\underline{\mathbf{v}}_1}{|\underline{\mathbf{v}}_1|}$$

$$\underline{\mathbf{v}}_2 = \hat{\underline{\mathbf{v}}}_+ = \underline{\mathbf{w}}_- = \begin{pmatrix} a_{22} - a_{11} \mp \sqrt{\Delta} \\ -2a_{21} \end{pmatrix}, \quad \tilde{\underline{\mathbf{v}}}_2 = \frac{\underline{\mathbf{v}}_2}{|\underline{\mathbf{v}}_2|}$$

- Substituição ortogonal:

$$\underline{\underline{\mathbf{V}}} = \begin{pmatrix} | & | \\ \tilde{\underline{\mathbf{v}}}_1 & \tilde{\underline{\mathbf{v}}}_2 \\ | & | \end{pmatrix}$$

- $\det \underline{\underline{\mathbf{V}}} = +1 \Rightarrow (\tilde{\underline{\mathbf{v}}}_1, \tilde{\underline{\mathbf{v}}}_2)$  orientados *positivamente*.

$$2xy = 1:$$

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$$2xy = (x \ y)^T \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

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$$f \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} y \\ x \end{pmatrix}$$

- Imediato, autovetores:  $\underline{\mathbf{v}}_1 = (1, 1)^T$  e  $\underline{\mathbf{v}}_2 = (-1, 1)^T$ !
- Autovalores 1 resp.  $-1$ !
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$$\det(\underline{\mathbf{A}} - \underline{\mathbf{I}}) = \begin{vmatrix} -\lambda & 1 \\ 1 & -\lambda \end{vmatrix} = \lambda^2 - 1 = 0 \Leftrightarrow \lambda = \pm 1$$

## $2xy = 1$ , cont.:

- $\lambda_1 = 1$ :  
 $\underline{\underline{\mathbf{A}}}-\underline{\underline{\mathbf{I}}} = \begin{pmatrix} -1 & 1 \\ 1 & -1 \end{pmatrix} \sim \begin{pmatrix} -1 & 1 \\ 0 & 0 \end{pmatrix} \underline{\underline{\mathbf{x}}} = \underline{\underline{\mathbf{0}}} \Leftrightarrow \underline{\underline{\mathbf{x}}} = t \begin{pmatrix} 1 \\ 1 \end{pmatrix}, t \in \mathbb{R}$

$$\underline{\underline{\mathbf{v}}}_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \Rightarrow \underline{\underline{\tilde{\mathbf{v}}}}_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

- $\lambda_2 = -1$ :  
 $\underline{\underline{\mathbf{A}}}+\underline{\underline{\mathbf{I}}} = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \sim \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix} \underline{\underline{\mathbf{x}}} = \underline{\underline{\mathbf{0}}} \Leftrightarrow \underline{\underline{\mathbf{x}}} = t \begin{pmatrix} -1 \\ 1 \end{pmatrix}, t \in \mathbb{R}$

$$\underline{\underline{\mathbf{v}}}_2 = \begin{pmatrix} -1 \\ 1 \end{pmatrix} \Rightarrow \underline{\underline{\tilde{\mathbf{v}}}}_2 = \underline{\underline{\hat{\mathbf{v}}}}_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

- Subst. ortogonal:

$$\underline{\underline{\mathbf{V}}} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} \cos \frac{\pi}{4} & -\sin \frac{\pi}{4} \\ \sin \frac{\pi}{4} & \cos \frac{\pi}{4} \end{pmatrix};$$

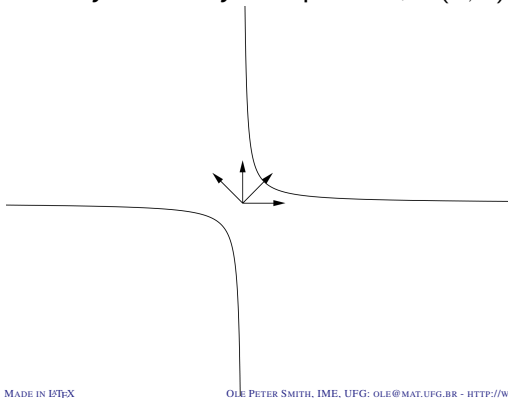
- $\det \underline{\underline{\mathbf{V}}} = 1$

## $2xy = 1$ , cont.:



$$\underline{\underline{\mathbf{B}}} = \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \underline{\underline{\mathbf{V}}}^{-1} \underline{\underline{\mathbf{A}}} \underline{\underline{\mathbf{V}}} = \underline{\underline{\mathbf{V}}}^T \underline{\underline{\mathbf{A}}} \underline{\underline{\mathbf{V}}}$$

- $1 = 2xy = x'^2 - y'^2$ : Hiperbole,  $C(0, 0)$  e  $a = b = 1$ .



$$2xy - \sqrt{2}ax = c:$$

•

$$\underline{\mathbf{b}} = - \begin{pmatrix} \sqrt{2}a \\ 0 \end{pmatrix}$$

•

$$\underline{\mathbf{b}}' = -\underline{\mathbf{v}}^T \begin{pmatrix} \sqrt{2}a \\ 0 \end{pmatrix} = -\frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} \sqrt{2}a \\ 0 \end{pmatrix} = \begin{pmatrix} -a \\ a \end{pmatrix}$$

•  $\underline{\mathbf{b}}^T \underline{\mathbf{r}} = \underline{\mathbf{b}}'^T \underline{\mathbf{r}}' = -ax' + ay'.$

•  $c = 2xy - \sqrt{2}a = x'^2 - y'^2 - ax' + ay' =$

$$(x'^2 - ax') - (y'^2 - ay') = \left(x' - \frac{a}{2}\right)^2 - \left(\frac{a}{2}\right)^2 - \left(y' - \frac{a}{2}\right)^2 - \left(\frac{a}{2}\right)^2$$

$$\left(x' - \frac{a}{2}\right)^2 - \left(y' - \frac{a}{2}\right)^2 - \frac{a^2}{2} \quad \Leftrightarrow$$

$$\left(x' - \frac{a}{2}\right)^2 - \left(y' - \frac{a}{2}\right)^2 = c + \frac{a^2}{2}$$

$$2xy - \sqrt{2}ax = c, \text{ cont.:}$$

- Hiperbole, roteado ângulo  $\frac{\pi}{4}$ .
- Centro:  $\underline{\mathbf{c}}' = \left(\frac{a}{2}, \frac{a}{2}\right)^T$ .

$$\underline{\mathbf{c}} = \underline{\mathbf{V}} \underline{\mathbf{c}}' = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} \frac{a}{2} \\ \frac{a}{2} \end{pmatrix} = \begin{pmatrix} 0 \\ \frac{a}{\sqrt{2}} \end{pmatrix}$$

- Semi-eixos:  $a = b = \sqrt{|\mathbf{c} + \frac{a^2}{2}|}$ .
- Assintotas:  $y' - \frac{a}{2} = \pm(x' - \frac{a}{2}) \Leftrightarrow x = 0 \vee y = \frac{a}{\sqrt{2}}$ .
- $c + \frac{a^2}{2} > 0$ : 1<sup>o</sup> e 3<sup>o</sup> quadrante.
- $c + \frac{a^2}{2} = 0$ : As assintotas.
- $c + \frac{a^2}{2} < 0$ : 2<sup>o</sup> e 4<sup>o</sup> quadrante.



Estes são meus Princípios.  
Se Você não Gosta deles, eu tenho Outros...  
*Groucho Marx*

Life *sure* is a Mystery to be Lived  
Not a Problem to be Solved  
Please Always Enjoy!

*Ole*